



(12) **United States Patent**
Quaid et al.

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(54) **SYSTEM AND METHOD FOR PERFORMING SURGICAL PROCEDURE USING DRILL GUIDE AND ROBOTIC DEVICE OPERABLE IN MULTIPLE MODES**

(58) **Field of Classification Search**
CPC A61B 17/17
See application file for complete search history.

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Related U.S. Application Data

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(57) **ABSTRACT**

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A61F 2/30 (2006.01)
(Continued)

System and method for performing a surgical procedure using a drill guide and a robotic device operable in multiple modes. The drill guide is mechanically coupled to the robotic device. A pre-defined virtual trajectory constrains movement of the drill guide. In a first mode, a user is able to manually manipulate the drill guide while movement of the drill guide is constrained by the pre-defined virtual trajectory. In a second mode, the robotic device operates autonomously, for instance, to perform service on the robotic device.

(52) **U.S. Cl.**
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20 Claims, 13 Drawing Sheets

